

METÓDY RIEŠENIA FYZIKÁLNYCH ÚLOH 1 leto19 – Príklady 1

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Príklad 1

We have D ducks and H hunters. Probability that a particular duck will not be hit is equal to probability that all hunters are aiming at other ducks. The probability that a hunter is aiming at some specific duck is $1/D$ and thus the probability of not being hit for a duck is

$$P_{\text{not hit}} = \left(1 - \frac{1}{D}\right)^H$$

and the average number of ducks to survive the ordeal is

$$N_{\text{escape}} = DP_{\text{not hit}} = D \left(1 - \frac{1}{D}\right)^H = \frac{(D-1)^H}{D^{H-1}} \approx 3.49 \quad \text{for } D = H = 10$$

Príklad 2

Stepping on the platform will lower it a distance D . This means that the spring constant of the platform spring is given by

$$kD = m_p g.$$

If the lump of clay is removed, then the equilibrium position of the platform would rise a distance A given by

$$kA = m_c g.$$

This would also be the amplitude of the oscillations after the clay is released, so

$$A_i = \frac{m_c g}{k}$$

The frequency of oscillation of the plate without the clay is

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m_p}}$$

The time for a complete oscillation is

$$T = 2\pi \sqrt{\frac{m_p}{k}}$$

If the clay falls a distance h , then

$$h = \frac{1}{2} g T^2 = 2\pi^2 g \frac{m_p}{k} = 2\pi^2 H.$$

When the plate is at the starting point it is at rest. The clay will hit it with a speed given by

$$v_0 = gT.$$

Conservation of momentum in an inelastic collision will then result in a final speed of the clay + platform system of

$$v_f = v_0 \frac{m_c}{m_c + m_p}.$$

The kinetic energy just after collision will be

$$K = \frac{1}{2} (m_c + m_p) v_f^2.$$

So the amplitude of the resulting oscillations will be given by

$$\frac{1}{2} k A_f^2 = \frac{1}{2} (m_c + m_p) v_f^2$$

or

$$A_f = v_f \sqrt{\frac{m_c + m_p}{k}}$$

Gluing stuff together

$$\begin{aligned}
 \frac{A_f}{A_i} &= \frac{v_f}{A_i} \sqrt{\frac{m_c + m_p}{k}}, \\
 &= \frac{v_0}{A_i} \frac{m_c}{m_c + m_p} \sqrt{\frac{m_c + m_p}{k}}, \\
 &= \frac{gTk}{m_c g} \frac{m_c}{m_c + m_p} \sqrt{\frac{m_c + m_p}{k}}, \\
 &= T \sqrt{\frac{k}{m_p + m_c}}
 \end{aligned}$$

And then, combining with our previous expression for T ,

$$\begin{aligned}
 \frac{A_f}{A_i} &= 2\pi \sqrt{\frac{m_p}{k}} \sqrt{\frac{k}{m_p + m_c}}, \\
 &= 2\pi \sqrt{\frac{m_p}{m_p + m_c}}
 \end{aligned}$$

If, instead, the clay manages to hit the platform at the top of an oscillation, then the distance the clay would fall would only be

$$h - 2A$$

and the time required would be

$$\frac{T}{2} = \pi \sqrt{\frac{m_p}{k}}.$$

Then

$$h - 2A = \frac{1}{2}g \left(\frac{T}{2}\right)^2,$$

where that complicated looking thing is actually

$$\frac{1}{4}h.$$

So

$$\begin{aligned}
 h &= \frac{1}{4}h + 2A, \\
 \frac{3}{8}h &= A, \\
 \frac{3}{4}\pi^2 D &= A.
 \end{aligned}$$

But from the very first two equations,

$$\frac{m_c}{m_p} = \frac{A}{D} = \frac{3}{4}\pi^2.$$

In this scenario the clay passes the platform three times: once at the highest point, once some distance further on, and once when the at the lowest point. That means that if A were smaller, it might be possible to find a value of A such that the clay just barely touches the platform once before hitting the platform at the bottom. Consequently, this is an *over* estimate for A , and an overestimate for m_c , and therefore, and overestimate for the ratio. A larger ratio would guarantee collision, the actual critical ratio would be smaller than this.

Príklad 3

C... Conservation of mechanical energy can be employed here. This gives $\Delta KE + \Delta PE = 0$ and we note that we have two forms of kinetic energy (translational and rotational). Incorporating both, we write $\Delta KE_{tr} + \Delta KE_{rot} + \Delta PE = 0 \rightarrow \left(\frac{1}{2}mv_f^2 - 0\right) + \left(\frac{1}{2}I\omega_f^2 - 0\right) + \left(0 - \frac{1}{2}kx_i^2\right) = 0$. Noting

from the equation sheet that $I_{cyl} = \frac{1}{2}MR^2$, we can write, using $v = r\omega$, that

$$\frac{1}{2}mv_f^2 + \frac{1}{2}\left(\frac{1}{2}MR^2\right)\omega^2 = \frac{1}{2}kx_i^2 \rightarrow mv^2 + \frac{1}{2}mv^2 = kx_i^2 \Rightarrow v_{cm} = \sqrt{\frac{4}{3}k/m} x_i = 1.15 m/s$$

Príklad 4

46. Podobne ako v úlohe 45 možno nájsť "zrkadlový" náboj q' (z vonkajšej strany guľovej plochy), ktorého veľkosť je $q' = -(a/\delta)q$ a je umiestnený vo vzdialenosti $d = a^2/\delta$ od stredu guľovej plochy. Náboj q bude priťahovaný ku guľovej ploche silou

$$f = \frac{1}{4\pi\epsilon_0} \frac{qq'}{(d-\delta)^2} = \frac{q^2}{4\pi\epsilon_0} \frac{a\delta}{(a^2-\delta^2)^2}$$

ktorá nezávisí od elektrického stavu gule, t.j. či je guľa uzemnená, izolovaná, nabitá alebo nenabitá.

Príklad 5

(a) Let the length of string on the table be r and the length hanging below be y . The mass m_1 is described by the polar coordinates (r, ϕ) . The fixed length constraint is $y + r = \ell$. The Lagrangian is

$$\begin{aligned} L &= \frac{1}{2}m_1(\dot{r}^2 + r^2\dot{\phi}^2) + \frac{1}{2}m_2\dot{y}^2 + m_2gy \\ &= \frac{1}{2}(m_1 + m_2)\dot{r}^2 + \frac{1}{2}m_1r^2\dot{\phi}^2 + m_2g(\ell - r) . \end{aligned}$$

(b) The angular momentum is conserved: $\dot{p}_\phi = 0$, with

$$p_\phi = \frac{\partial L}{\partial \dot{\phi}} = m_1r^2\dot{\phi} .$$

The equation of motion for r yields

$$\begin{aligned} (m_1 + m_2)\ddot{r} &= m_1r\dot{\phi}^2 - m_2g \\ &= \frac{p_\phi^2}{m_1r^3} - m_2g \equiv -\frac{\partial U_{\text{eff}}}{\partial r} , \end{aligned}$$

where the effective potential is

$$U_{\text{eff}} = \frac{p_\phi^2}{2m_1r^2} + m_2gr .$$

The condition for stationary m_2 is $\dot{r} = \ddot{r} = 0$, which requires $U'_{\text{eff}}(r) = 0$. This, in turn, has the solution $r = a$, with

$$a = \left(\frac{p_\phi^2}{m_1 m_2 g} \right)^{1/3} .$$

(c) The tension in the string along the table is radial, hence there are no torques, and p_ϕ is conserved.

(d) We write $r = a + \eta$ and expand the equation of motion:

$$(m_1 + m_2) \ddot{\eta} = -U''_{\text{eff}}(a) \eta + \mathcal{O}(\eta^2) .$$

The solution is

$$\eta(t) = \eta_0 \cos(\omega t + \delta) ,$$

where the oscillation frequency is

$$\omega = \sqrt{\frac{U''_{\text{eff}}(a)}{m_1 + m_2}} = \sqrt{\frac{3m_2 g}{(m_1 + m_2)a}} .$$