

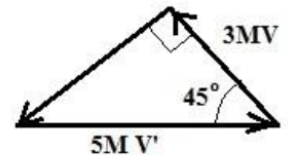
METÓDY RIEŠENIA FYZIKÁLNYCH ÚLOH zima20 – Príklady 2

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Príklad 1

METHOD #1: Vector Addition: Since $\vec{p}_{3M} + \vec{p}_{4M} + \vec{p}_{5M} = 0$ as the object was initially at rest, $\vec{p}_{3M} + \vec{p}_{4M} = -\vec{p}_{5M}$. Since p_{3M} and p_{4M} form a right angle with p_{5M} as the hypotenuse, we use right-triangle trig to obtain $\cos 45^\circ = \frac{p_{3M}}{p_{5M}} \Rightarrow \frac{1}{\sqrt{2}} = \frac{3MV}{5MV'} \Rightarrow V' = \frac{3\sqrt{2}}{5}V$



METHOD #2: Momentum components: By writing linear momentum conservation in both the x and y directions, we have $\Delta p_x = 0 \Rightarrow \Delta p_{3M_x} + \Delta p_{4M_x} + \Delta p_{5M_x} = 0 \Rightarrow$

$$3M(-V \cos 45^\circ - 0) + 4M(-V' \cos 45^\circ - 0) + 5M(V'' - 0) = 0$$

$$-\frac{3V}{\sqrt{2}} - \frac{4V'}{\sqrt{2}} + 5V'' = 0 \Rightarrow 5\sqrt{2} V'' = 3V + 4V'$$

$$\Delta p_y = 0 \Rightarrow \Delta p_{3M_y} + \Delta p_{4M_y} + \Delta p_{5M_y} = 0 \Rightarrow$$

$$3M(-V \cos 45^\circ - 0) + 4M(-V' \cos 45^\circ - 0) + 5M(V'' - 0) = 0$$

$$3M(V \sin 45^\circ - 0) + 4M(-V' \sin 45^\circ - 0) + 5M(0 - 0) = 0$$

$$V' = \frac{3}{4}V$$

So, by substituting this result into the y-expression gives $5\sqrt{2} V'' = 3V + 3V \Rightarrow V'' = \frac{6}{5\sqrt{2}}V = \frac{3\sqrt{2}}{5}V$

Príklad 2

$$\vec{E}(\underline{r}, t) = \hat{y} \frac{1}{2} [f(x-ct) + f(x+ct)]$$

$$\vec{B}(\underline{r}, t) = \hat{z} \frac{1}{2c} [f(x-ct) - f(x+ct)]$$

Príklad 3

(a) The Lagrangian is

$$L = \frac{1}{2}m_1(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) + \frac{1}{2}m_2(\dot{\rho}^2 + \rho^2 \dot{\phi}^2) - V(\alpha x + \beta y + \gamma z, y + a\phi).$$

(b) The Lagrangian is rendered invariant under time-independent transformations satisfying $dV = 0$ and $d\rho = 0$, i.e.

$$\alpha dx + \beta dy + \gamma dz = 0, \quad dy + a d\phi = 0, \quad d\rho = 0.$$

The two-parameter family may be written as

$$x(\zeta_1, \zeta_2) = x - \frac{\gamma}{\alpha} \zeta_1 + \frac{\beta}{\alpha} \zeta_2$$

$$y(\zeta_1, \zeta_2) = y - \zeta_2$$

$$z(\zeta_1, \zeta_2) = z + \zeta_1$$

$$\phi(\zeta_1, \zeta_2) = \phi + a^{-1} \zeta_2$$

$$\rho(\zeta_1, \zeta_2) = \rho.$$

The associated conserved quantities are

$$\Lambda_i = \sum_{\sigma} \frac{\partial L}{\partial \dot{q}_{\sigma}} \frac{\partial q_{\sigma}}{\partial \zeta_i} \Big|_{\zeta_i},$$

whence

$$\Lambda_1 = -\frac{\gamma}{\alpha} m_1 \dot{x} + m_1 \dot{z}, \quad \Lambda_2 = \frac{\beta}{\alpha} m_1 \dot{x} - m_1 \dot{y} + a^{-1} m_2 \rho^2 \dot{\phi}.$$

(c) Since $\partial L / \partial t = 0$, the total energy is also conserved:

$$E = \frac{1}{2} m_1 (\dot{x}^2 + \dot{y}^2 + \dot{z}^2) + \frac{1}{2} m_2 (\dot{\rho}^2 + \rho^2 \dot{\phi}^2) + V(\alpha x + \beta y + \gamma z, y + a\phi).$$

Příklad 4

Solution : Fermat's principle $\delta \int n(\vec{r}) dl = 0$.

Assuming a circular orbit of radius $R+h$, we get

$$\frac{d}{dh} [n(h) \cdot 2\pi (R+h)] = 0, \quad \frac{n'(h)}{n(h)} = -\frac{1}{R+h},$$

$$\underline{h = \frac{1}{2} \left(\frac{n_0}{\alpha} - R \right)}.$$

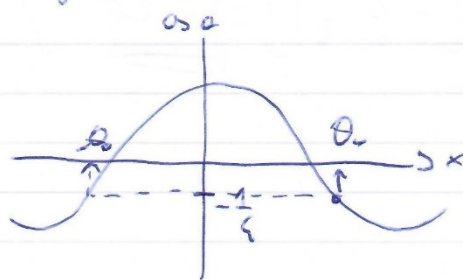
PRÍKLAD 4:

rovnice pre hyperbolu v tvaru

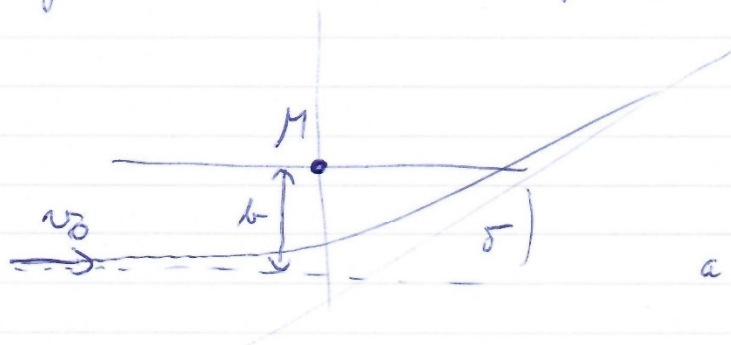
$$r = \frac{r_0}{1 + \epsilon \cos \theta} \quad (1) \quad \text{kde} \quad \epsilon = \sqrt{1 + \frac{2EL^2}{m^3 k^2}} > 1$$

kde $k = GM$

mať pohyb iba keď $\cos \theta < -\frac{1}{\epsilon}$



výsledok (1) keď dáva pohyb pre rozbíhajúceho $2\theta_2 = \Delta\theta$



z obrázku $\Delta\theta = \pi + \delta$

ktoré kvôli tomu

a teda $\delta = 2\theta_0 - \pi$

$$E = \frac{1}{2} m v_0^2 \Rightarrow \frac{2EL^2}{m^3 k^2} = \frac{v_0^4 b^2}{G^2 M^2} \quad \text{v limite } v_0 \gg 1 \text{ máme}$$

$$L = m v_0 b \quad \frac{1}{\epsilon} \approx \frac{GM}{E v_0^2 b}$$

keď $\theta_0 \approx \frac{\pi}{2} \Rightarrow \cos \theta_0 \approx \frac{\pi}{2} - \theta_0$ a teda $\theta_0 = \frac{\pi}{2} + \frac{GM}{v_0^2 b}$

kvôli tomu

$$\delta = \frac{2GM}{v_0^2 b}$$