

## METÓDY RIEŠENIA FYZIKÁLNYCH ÚLOH 3 leto21 – Príklady 2

### VZOROVÉ RIEŠENIA

Cvičenie 11.3.2021

#### Príklad 1

2. (a) Since elements are independent, we can compute the partition function for one element,  $Z_1 = 1 + e^{-\beta\epsilon}$ , and then compute  $Z_N = (1 + e^{-\beta\epsilon})^N$ . Since the energy is just proportional to the number of elements in state  $b$ , we can compute

$$\langle N_B \rangle = -\frac{\partial \ln Z}{\partial \beta\epsilon} = \frac{N}{e^{\beta\epsilon} + 1}$$

Note that  $\langle N_A \rangle = N - \langle N_B \rangle$ , so

$$\langle L \rangle = a \langle N_A \rangle + b \langle N_B \rangle = Na + \frac{N(b-a)}{e^{\beta\epsilon} + 1}$$

$$(b) \langle L^2 \rangle = \langle (aN_A + bN_B)^2 \rangle = \langle (aN + (b-a)N_B)^2 \rangle$$

$$= a^2N^2 + 2a(b-a)N \langle N_B \rangle + (b-a)^2 \langle N_B^2 \rangle$$

$$\langle L \rangle^2 = [aN + (b-a) \langle N_B \rangle]^2 = a^2N^2 + (b-a)^2 \langle N_B \rangle^2 + 2a(b-a)N \langle N_B \rangle$$

so

$$\langle L^2 \rangle - \langle L \rangle^2 = (b-a)^2 [\langle N_B^2 \rangle - \langle N_B \rangle^2]$$

and

$$\langle N_B^2 \rangle - \langle N_B \rangle^2 = \frac{\partial^2}{\partial (\beta\epsilon)^2} \ln Z = \frac{N e^{\beta\epsilon}}{(e^{\beta\epsilon} + 1)^2}$$

giving RMS fluctuation

$$\sqrt{\langle L^2 \rangle - \langle L \rangle^2} = \frac{\sqrt{N}(b-a)}{e^{\beta\epsilon/2} + e^{-\beta\epsilon/2}}$$

(c) If we force length to be  $L$  we force  $N_B = (L - Na)/(b - a)$ . The energy is  $E = N_B\epsilon$ , and the entropy is just the log of the number of ways to choose  $N_B$  of the monomers to be in state  $b$ ,  $S = k_B \ln \binom{N}{N_B}$ . So,

$$S = k_B \ln \frac{N!}{N_B!(N - N_B)!}$$

which can be written in the large  $N$  and  $N_B$  limit as

$$S = k_B \left[ N_B \ln \frac{N}{N_B} + (N - N_B) \ln \frac{N}{N - N_B} \right]$$

so

$$F = E - ST = N_B\epsilon + k_B T \left[ N_B \ln \frac{N_B}{N} + (N - N_B) \ln \frac{N - N_B}{N} \right]$$

where  $N_B/N = (L - Na)/[N(b - a)]$  and where  $1 - N_B/N = (Nb - L)/[N(b - a)]$ .

(d) Force is given by  $L$  derivative of free energy at fixed temperature

$$f = \left( \frac{\partial F}{\partial L} \right)_T = \left( \frac{\partial N_B}{\partial L} \right) \left( \frac{\partial F}{\partial N_B} \right)$$

$$f = (\epsilon + k_B T [\ln N_B/N - \ln(1 - N_B/N)]) / (b - a)$$

or

$$f = \frac{\epsilon + k_B T \ln \frac{L - Na}{Nb - L}}{b - a}$$

Note force diverges to infinite tension if  $L \rightarrow Nb$ ; also force diverges to infinite compression if  $L \rightarrow Na$ .

### Príklad 2

(a) Easily checked by substitution.

(b) We find

$$a = \frac{\pi_x + i\pi_y}{\sqrt{2}\hbar} \ell, \quad a^\dagger = \frac{\pi_x - i\pi_y}{\sqrt{2}\hbar} \ell.$$

(c) Let  $\varepsilon_1 = \sqrt{2}\hbar v/\ell$ , then the Schrödinger equation becomes

$$\frac{\varepsilon}{\varepsilon_1} \psi_A = a^\dagger \psi_B, \quad \frac{\varepsilon}{\varepsilon_1} \psi_B = a \psi_A, \quad \text{or} \quad \frac{\varepsilon^2}{\varepsilon_1^2} \psi_A = a^\dagger a \psi_A, \quad \frac{\varepsilon^2}{\varepsilon_1^2} \psi_B = a a^\dagger \psi_B.$$

(d) By the indicated analogy  $\varepsilon_n^2/\varepsilon_1^2$  must be a nonnegative integer. We can write the set of energy levels (which includes  $\varepsilon_n < 0$ ) as

$$\varepsilon_n = \text{sign}(n) \frac{\hbar v}{\ell} |2n|^{1/2}, \quad n \in \mathbb{Z}.$$

### Príklad 3

(a) Show that the potential  $\Phi = VR/r$  satisfies the required boundary conditions on the plane  $\mathcal{C}$  separating dielectrics as well as on the sphere.

**Solution:**

$$D = \varepsilon_{1,2} E \text{ and } E = -\nabla\Phi = VR\hat{r}/r^2.$$

$$\text{On the plane: } (D_1)_n = (D_2)_n = 0 \text{ and } (E_1)_t = (E_2)_t = VR/r^2.$$

$$\text{On the sphere: } \Phi|_{r=R} = V.$$

(b) Find the free charge density  $\sigma$  on the surface of the conducting sphere and the total amount of free charge  $Q$  on it.

$$\text{Solution: } \sigma = D_r = \varepsilon_{1,2} V/R.$$

$$\text{Total charge } Q = 2\pi R^2(\sigma_1 + \sigma_2) = 2\pi(\varepsilon_1 + \varepsilon_2)VR.$$

(c) Find the bound charge densities  $\sigma_b$  on the spherical boundaries  $\mathcal{A}$  and  $\mathcal{B}$  of the dielectrics.

$$\text{Solution: } \sigma_b|_{\mathcal{A},\mathcal{B}} = -P_r = (\varepsilon_0 E - D)_r = (\varepsilon_0 - \varepsilon_{1,2})E_r = -(\varepsilon_{1,2} - \varepsilon_0)V/R.$$

(d) Find the bound charge density  $\sigma_b$  on the flat boundary  $\mathcal{C}$  between the dielectrics.

Solution: ( $[...]$  denotes discontinuity)  $\sigma_b|_{\mathcal{C}} = -[P_n] = [\varepsilon_0 E_n] = 0$ .

#### Príklad 4

In cylindrical coordinates the length element is  $ds = \sqrt{dr^2 + r^2 d\phi^2 + dz^2}$  and since the mountain is described by the equation  $z = -r$  then the length element on the mountain is given by

$$ds = \sqrt{2dr^2 + r^2 d\phi^2}. \quad (1)$$

To find the optimal path we need to minimize the functional

$$\mathcal{P}[r(\phi)] = \int \sqrt{2dr^2 + r^2 d\phi^2} = \int d\phi \sqrt{r^2 + 2\dot{r}^2} = \int d\phi \mathcal{L}(r, \dot{r}, \phi). \quad (2)$$

Consequently, the shortest path is the solution of

$$\frac{d}{d\phi} \frac{\partial \mathcal{L}}{\partial \dot{r}} - \frac{\partial \mathcal{L}}{\partial r} = 0 \quad (3)$$

$$\frac{2\ddot{r}}{\sqrt{r^2 + 2\dot{r}^2}} - \frac{2\dot{r}(\dot{r}r + 2\ddot{r}r)}{(r^2 + 2\dot{r}^2)^{3/2}} - \frac{r}{\sqrt{r^2 + 2\dot{r}^2}} = 0 \quad (4)$$

$$2\ddot{r}(r^2 + 2\dot{r}^2) - 2\dot{r}(\dot{r}r + 2\ddot{r}r) - r(r^2 + 2\dot{r}^2) = 0 \quad (5)$$

$$r^2 + 4\dot{r}^2 - 2\ddot{r}r = 0. \quad (6)$$

With  $r = 1/u$  then  $\dot{r} = -\dot{u}/u^2$  and  $\ddot{r} = 2\dot{u}^2/u^3 - \ddot{u}/u^2$  which leads to

$$\frac{1}{u^2} + \frac{4\dot{u}^2}{u^4} - \frac{2}{u} \left( \frac{2\dot{u}^2}{u^3} - \frac{\ddot{u}}{u^2} \right) = 0, \quad \frac{1}{u^2} + \frac{2\ddot{u}}{u^3} = 0, \quad \ddot{u} + \frac{1}{2}u = 0. \quad (7)$$

The general solution for the optimal path is thus  $u(\phi) = A \cos \frac{\phi}{\sqrt{2}} + B \sin \frac{\phi}{\sqrt{2}}$ . From the initial position constraint  $(r_0, \phi_0) = (1, 0)$ , we obtain  $u(0) = A$  which leads to  $A = 1$ . Similarly, from the final position constraint  $(r_1, \phi_1) = (1, \pi)$  we obtain  $u(\pi) = \cos \frac{\pi}{\sqrt{2}} + B \sin \frac{\pi}{\sqrt{2}}$  giving  $B = (1 - \cos \frac{\pi}{\sqrt{2}}) / \sin \frac{\pi}{\sqrt{2}}$ . Putting everything together we obtain that the shortest path to the refuge is the one described by the equation

$$r(\phi) = \cos \frac{\pi}{2\sqrt{2}} \sec \frac{\pi - 2\phi}{2\sqrt{2}}. \quad (8)$$